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CONTROL SYSTEMS ENGINEERING SIXTH EDITION. Antenna Azimuth Position Control System Antenna Potentiometer Fixed field  $e_m(t)$  Armature Gear Layout Potentiometer  $e_i(t)$  Desired azimuth angle input Differential amplifier and power amplifier Motor Schematic Desired azimuth angle input  $e_i(t)$   $n$ -turn potentiometer  $80(t)$  Azimuth angle output Differential preamplifier Power amplifier  $v_p(t)$   $e_a(t)$   $V_i(t) + v_o(t)$  —  $\text{kg}\cdot\text{m}^2$   $\text{N}\cdot\text{m}$   $\text{s}/\text{rad}$   $\text{V}\cdot\text{s}/\text{rad}$   $\text{N}\cdot\text{m}/\text{A}$   $n \dots$

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